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Version 2, June 1991

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Version 3.1, 31 March 2009

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25	COPYRIGHT © 1986 Gary S. Brown. You may use this program, or code or tables extracted from it, as desired without restriction. First, the polynomial itself and its table of feedback terms. The polynomial is X^32+X^26+X^23+X^22+X^16+X^12+X^11+X^10+X^8+X^7+X^5+X^4+X^2+X^1+X^0 Note that we take it "backwards" and put the highest-order term in the lowest-order bit. The X^32 term is "implied"; the LSB is the X^31 term, etc. The X^0 term (usually shown as "+1") results in the MSB being 1. Note that the usual hardware shift register implementation, which is what we're using (we're merely optimizing it by doing eight-bit chunks at a time) shifts bits into the lowest-order term. In our implementation, that means shifting towards the right. Why do we do it this way? Because the calculated CRC must be transmitted in order from highest-order term to lowest-order term. UARTs transmit characters in order from LSB to MSB. By storing the CRC this way, we hand it to the UART in the order low-byte to high-byte; the UART sends each low-bit to hight-bit; and the result is transmission bit by bit from highest- to lowest-order term without requiring any bit shuffling on our part. Reception works similarly. The feedback terms table consists of 256, 32-bit entries. Notes: The table can be generated at runtime if desired; code to do so is shown later. It might not be obvious, but the feedback terms simply represent the results of eight shift/xor operations for all combinations of data and CRC register values. The values must be right-shifted by eight bits by the "updcrc" logic; the shift must be unsigned (bring in zeroes). On some hardware you could probably optimize the shift in assembler by using byte-swap instructions. Polynomial \$edb88320 Ported to QNX by Thorsten Lockert and Dan Hildebrand, September, 1989
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113	See GPL #36 Copyright © 1994-1996, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains a fast, not so accurate integer implementation of the forward DCT (Discrete Cosine Transform). A 2-D DCT can be done by 1-D DCT on each row followed by 1-D DCT on each column. Direct algorithms are also available, but they are much more complex and seem not to be any faster when reduced to code. This implementation is based on Arai, Agui, and Nakajima's algorithm for scaled DCT. Their original paper (Trans. IEICE E-71(11):1095) is in Japanese, but the algorithm is described in the Pennebaker & Mitchell JPEG textbook (see REFERENCES section in file README). The following code is based directly on figure 4-8 in P&M. While an 8-point DCT cannot be done in less than 11 multiplies, it is possible to arrange the computation so that many of the multiplies are simple scalings of the final outputs. These multiplies can then be folded into the multiplications or divisions by the JPEG quantization table entries. The AA&N method leaves only 5 multiplies and 29 adds to be done in the DCT itself. The primary disadvantage of this method is that with fixed-point math, accuracy is lost due to imprecise representation of the scaled quantization values. The smaller the quantization table entry, the less precise the scaled value, so this implementation does worse with high- quality-setting files than with low-quality ones. See OO #17
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117	Copyright © 1995-1997, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains Huffman entropy encoding routines for progressive JPEG. We do not support output suspension in this module, since the library currently does not allow multiple-scan files to be written with output suspension.
118	Copyright © 1991-1996, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains downsampling routines. Downsampling input data is counted in "row groups". A row group is defined to be max_v_samp_factor pixel rows of each component, from which the downsampler produces v_samp_factor sample rows. A single row group is processed in each call to the downsampler module. The downsampler is responsible for edge-expansion of its output data to fill an integral number of DCT blocks horizontally. The source buffer may be modified if it is helpful for this purpose (the source buffer is allocated wide enough to correspond to the desired output width). The caller (the prep controller) is responsible for vertical padding. The downsampler may request "context rows" by setting need_context_rows during startup. In this case, the input arrays will contain at least one row group's worth of pixels above and below the passed-in data; the caller will create dummy rows at image top and bottom by replicating the first or last real pixel row. An excellent reference for image resampling is Digital Image Warping, George Wolberg, 1990. Pub. By IEEE Computer Society Press, Los Alamitos, CA. ISBN 0-8186-8944-7. The downsampling algorithm used here is a simple average of the source pixels covered by the output pixel. The hi-falutin sampling literature refers to this as a "box filter". In general the characteristics of a box filter are not very good, but for the specific cases we normally use (1:1 and 2:1 ratios) the box is equivalent to a "triangle filter" which is not nearly so bad. If you intend to use other sampling ratios, you'd be well advised to improve this code. A simple input-smoothing capability is provided. This is mainly intended for cleaning up color-dithered GIF input files (if you find it inadequate, we suggest using an external filtering program such as pnmconvol). When enabled, each input pixel P is replaced by a we
119	Copyright © 1994-1996, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains the compression preprocessing controller. This controller manages the color conversion, downsampling, and edge expansion steps. Most of the complexity here is associated with buffering input rows as required by the downsampler. See the comments at the head of jcsample.c for the downsampler's needs.
120	Copyright © 1991-1996, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains a slow-but-accurate integer implementation of the forward DCT (Discrete Cosine Transform). A 2-D DCT can be done by 1-D DCT on each row followed by 1-D DCT on each column. Direct algorithms are also available, but they are much more complex and seem not to be any faster when reduced to code. This implementation is based on an algorithm described in C. Loeffler, A. Ligtenberg and G. Moschytz, "Practical Fast 1-D DCT Algorithms with 11 Multiplications", Proc. Int'l. Conf. on Acoustics, Speech, and Signal Processing 1989 (ICASSP '89), pp. 988-991. The primary algorithm described there uses 11 multiplies and 29 adds. We use their alternate method with 12 multiplies and 32 adds. The advantage of this method is that no data path contains more than one multiplication; this allows a very simple and accurate implementation in scaled fixed-point arithmetic, with a minimal number of shifts.
121	Copyright © 1995-1998, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains library routines for transcoding compression, that is, writing raw DCT coefficient arrays to an output JPEG file. The routines in jcapimin.c will also be needed by a transcoder.

122	
122	Copyright © 1994-1998, Thomas G. Lane. This file is part of the Independent JPEG Group's software. For conditions of distribution and use, see the accompanying README file. This file contains application interface code for the decompression half of the JPEG library. These are the "minimum" API routines that may be needed in either the normal
	full-decompression case or the transcoding-only case. Most of the routines intended to be called directly by an application are in this file or in jdapistd.c. But also see jcomapi.c for routines shared by compression and decompression, and jdtrans.c for the transcoding case.
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120	distribution and use, see the accompanying README file. This file contains application interface code for the decompression half of the JPEG library. These are the "standard" API routines that are used in the normal full-decompression case. They are not used by a transcoding-only application. Note that if an application links in
124	jpeg_start_decompress, it will end up linking in the entire decompressor. We thus must separate this file from jdapimin.c to avoid linking the whole decompression library into a transcoder. Intentionally blank
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primitive type sizes for @, I, and so on: a An ASCII string, will be null padded. A An ASCII string, will be space padded. B A bit string, low-to-high order. B A bit string, high-low-forer. B A bit string, high ontri first. C A signed char value. C An unsigned char value. S A signed short (16-bit) value. I A signed integer (32-bit) value. I An unsigned integer (32-bit) value. I A signed long (64-bit) value. I A short in 'network' byte order. N An integer in 'network' byte order. F A single-precision float in IEEE format. D A double-precision float in IEEE format. P A pointer to a string. X A null byte. X Back up one byte. @ Null-fill to absolute position. U A uuencoded string. Each letter may be followed by a number giving the repeat count. Together the letter and repeat count make a field specifier. Field specifiers may be separated by whitespace, which will be ignored. 158 Disclaimer of Warranty These software programs are available to the user without any license fee or royalty on an "as is" basis. The MPEG Software Simulation Group disclaims any and all warranties, whether express, implied, or statuary, including any implied warranties or merchantability or of fitness for a particular purpose. In no event shall the copyright-holder be liable for any incidental, punitive, or consequential damages of any kind whatsoever arising from the use of these programs. This disclaimer of warranty extends to the user of these programs unders' customers, employees, agents, transferees, successors, and assigns. The MPEG Software Simulation Group does not represent or warrant that the programs furnished hereunder are free of infringement of any third-party patents. Commercial implementations of MPEG-1 and MPEG-2 video, including shareware, are subject to royalty fees to patent holders. Many of these patents are general enough such that they are unavoidable regardless of implementation design. Some of these routines (autocorrelator, LPC coefficient estimator) are derived from code written by Jutta Degener and Carsten Bor	156	Intentionally blank
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