

Sysmac Library for NJ/NX/NY Controller

SYSMAC-XR003

MC Tool Box Library



✓ Easily connect an inverter to a PLC to drive a general-purpose motor.

Issue 1

If an inverter is installed near a motor, the wiring can be complicated due to the long distance between the inverter and PLC.

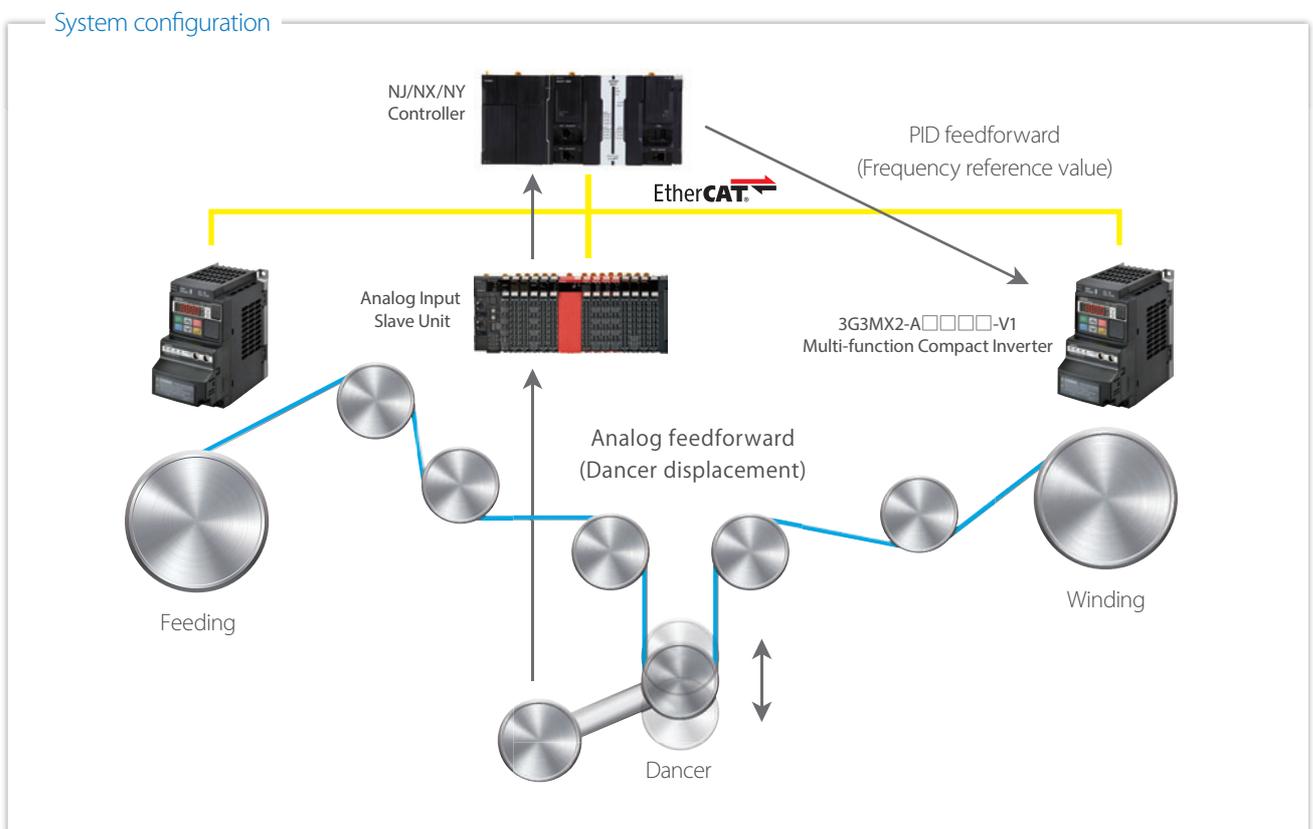
Issue 2

When an induction motor is used for speed control and simple positioning, it takes time to create a feedback control program.

MC Tool Box Library offers solution!

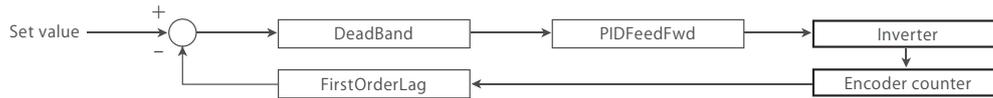
The NJ/NX Machine Automation Controller and the NY Industrial PC Platform can be connected to inverters and I/O devices via EtherCAT using LAN cables, which makes wiring simple.

Stable control can be achieved by combining Function Blocks in this library even when an inverter is used.



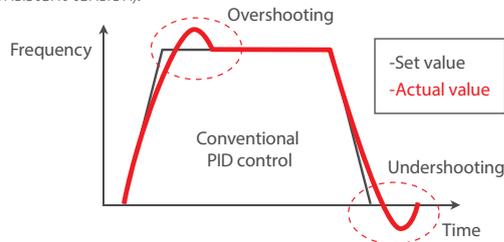
[Example] Tension control program using the MC Tool Box Library

NJ/NX/NY Controller



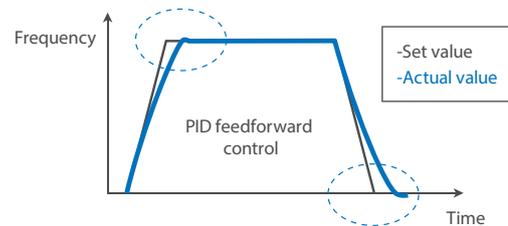
From

The motor speed quickly reaches the set speed but is not constant (= inconsistent tension).



To

The motor speed quickly reaches the set speed and is constant (= constant tension).



The NJ/NX/NY Controller executes sequence control, motion control, and I/O refreshing in the same control period. The calculation results of feedback control can be output in a short fixed cycle. This means the motor can constantly receive commands.

Compatible Models

Name	Model	Version
Machine Automation Controller NJ/NX CPU Unit	NX701-1□□□/NJ101-□□□□	Version 1.10 or later
	NJ501-□□□□/NJ301-□□□□	Version 1.08 or later
	NX1P2-□□□□□(1)	Version 1.13 or later
	NX102-□□□□	Version 1.30 or later
Industrial PC Platform NY IPC Machine Controller	NY5□□-1	Version 1.12 or later
	NY5□□-5	Version 1.18 or later
Automation Software Sysmac Studio	SYSMAC-SE2□□□	Version 1.14 or higher
MX2-V1 Multi-function Compact Inverter	3G3MX2-A□□□□-V1	Version 1.00 or later

Function Block (FB) Specifications

Name	FB name	Description
PID Feedforward	PIDFeedFwd	Performs PID feedforward processing according to a specified parameter table.
First Order Lag	FirstOrderLag	Processes a first order lag according to a specified parameter table.
Phase Lead Lag	LeadLag	Performs phase lead lag processing according to a specified parameter table.
Deadband Control without Output Offset	DeadBand	Controls a deadband that does not create an offset with the processing result.

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Note: Do not use this document to operate the Unit.

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