# E6J-C

CSM\_E6J-C\_DS\_E\_4\_3

# **Ultracompact Rotary Encoder with External Diameter of 20 mm**

- · Incremental model
- External diameter of 20 mm.
- Resolution of up to 1,000 ppr.
- Both Solid-shaft Models and Hollow-shaft Models are available.





Be sure to read Safety Precautions on page 4

# **Ordering Information**

### Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Shaft	Model
5 VDC	NPN open-collector output	100, 200, 360, 600	Shaft model	E6J-CWZ1C (resolution) 1M Example: E6J-CWZ1C 100P/R 1M
		1000		
	Voltage output	100, 200, 360, 600	Shaft model	E6J-CWZ1E (resolution) 1M Example: E6J-CWZ1E 100P/R 1M
		1000	Shall model	
	Voltage output	360, 600	Hollow shaft	E6J-CWZ1EA2 (resolution) 1M Example: E6J-CWZ1EA2 360P/R 1M
		1000		

# Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks
Coupling	E69-C02B	Included in the shaft model.

Refer to Accessories for details.

# **Ratings and Specifications**

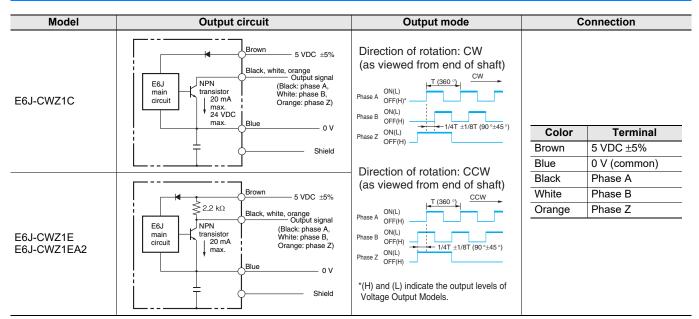
Item	Model	E6J-CWZ1C	E6J-CWZ1E	E6J-CWZ1EA2		
Shaft		Shaft Shaft dia. 2 mm, Length 10 mm		Hollow shaft Hollow shaft dia. 2 mm, Depth 10 mm		
Rated voltage		5 VDC ±5%				
Current consumption*1		40 mA max.				
Resolution (pulses/rotation)		100, 200, 360, 600, 1000		360, 600, 1000		
Output phases		Phases A, B, and Z				
Output configuration		NPN open-collector output Voltage output (NPN)				
Output capacity		Applied voltage: 24 VDC max. Load current: 20 mA max. Residual voltage: 0.5 V max. (at load current of 20 mA)	Output resistance: $2.2 \text{ k}\Omega$ Load current: $20 \text{ mA}$ max. Residual voltage: $0.5 \text{ V}$ max. (at load current of $20 \text{ mA}$ )			
Rise and fall times of output		2 μs max. (Cable length: 1 m, Load current: 20 mA)				
Maximum response frequency*2		100 kHz (50 kHz when using phase Z reset)				
Phase difference between outputs		90°±45° between A and B				
Direction of rotation		Phase A precedes in CW (as viewed from end of shaft).				
Starting torque		1 mN·m max.				
Moment of inertia	100P/R	$0.034 \times 10^{-7} \text{ kg} \cdot \text{m}^2$				
Moment of mertic	200P/R min.	$0.045 \times 10^{-7} \text{ kg} \cdot \text{m}^2$		$0.351 \times 10^{-7} \text{ kg} \cdot \text{m}^2$		
Shaft loading	Radial	1.9 N				
Onait locating	Thrust	1.9 N				
Maximum permissible speed		6,000 r/min				
Protective circuits		Power supply reverse polarity protection				
Ambient temperature range		Operating: -10 to 70°C (with no icing and condensation), Storage: -20 to 80°C (with no icing and condensation)				
Ambient humidity range		Operating/Storage: 35% to 85% (with no condensation)				
Insulation resistance		Excluded because of capacitor ground.				
Dielectric strength		Excluded because of capacitor ground.				
Vibration resistance		Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y and Z directions				
Shock resistance		Destruction: 500 m/s² 3 times each in X, Y and Z directions				
Degree of protection		IEC 60529 IP40				
Connection method		Pre-wired Models (Standard cable length: 1 m)				
	Case	Aluminum				
Material	Encoder	Aluminum				
	Shaft	SUS404	SUS304			
Weight (packed state)		Approx. 40 g				
Accessories		Instruction manual, Coupling, L-shaped wrench (M0.9)  Instruction manual, L-shaped wrench (M0.9)		Instruction manual, L-shaped wrench (M0.9)		

Maximum response frequency × 60 Maximum electrical response speed (rpm) = -Resolution

This means that the E6J-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

<sup>\*1.</sup> An inrush current of approximately 3 A will flow for approximately 10 μs when the power is turned ON.
\*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

# **I/O Circuit Diagrams**



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

2. The capacitor (0.1μF, 100 V) is connected between 0 V and FG (frame ground) of a circuit.

3. Normally, connect shield to 0 V or to an external ground.

# **Safety Precautions**

## Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



#### **Precautions for Safe Use**

#### **Installation Environment**

- Do not use in an environment where combustible or explosive gas is present
- Do not keep or use in an environment where the E6J-C is exposed to water, oil, chemicals, steam or dust. The E6J-C is damaged or burned out due to an internal circuit disconnection or short.
- To ensure safe operation and maintenance of the product, install it away from high-voltage devices and power devices.

#### **Power Supply and Wiring**

- Never apply the voltage and AC power that exceed the <u>rated</u> voltage (5 VDC ±5%). This may damage or burn out the product.
- Do not make the wiring while it is supplying power. This may damage the product or cause an electric shock.
- Do not short the load. This may damage or burn out the product.

#### Others

- Do not attempt to disassemble, repair, or modify the product.
- When disposing of the product, treat it as industrial waste.

#### **Precautions for Correct Use**

Do not use the product in atmospheres or environments that exceed product ratings.

#### Mounting

- The Rotary Encoder is composed of high-precision parts. Dropping the Rotary Encoder may damage some of its functions. Care should be taken when handling.
- $\bullet$  When securing this product with screws, do not exceed 0.15 N·m for tightening torque.

- If wiring after securing the Encoder, do not pull on the cable with a force exceeding 12 N. Also, do not apply shock to the Encoder or shaft (hollow shaft).
- When a mounting error (eccentricity, declination) is wide, excessive load is applied (as 1.9 N both for shaft loading radial and thrust), and the E6J-C is damaged and the life of that will be extremely shorten.

#### **Mounting of Hollow Shaft**

- The diameter of the mating shaft must be  $2^{-0.004}_{-0.012}$  mm, and the insert length must be 4 to 9.5 mm.
- Prepare leaf spring of flanges not to apply the load that exceeds a shaft permissible load.
- Use the Allen set screw provided with the hollow shaft to secure the shaft. Use a tightening torque of 0.15 N·m and apply screw lock glue to the screw to prevent it from becoming loose.

#### Wiring

- If a surge occurs in the power supply used, connect a surge absorber between power supplies and suppress the surge. To avoid a noise or other errors, shorten the wiring for the encoder as much as possible.
- When the length of the rotary encoder cable is extended, check the cable type and response frequency. There is a tendency that the residual voltage increases or a waved distortion occurs, due to changes in the cable resistance and the capacity between cables.
- Do not lay the cables in parallel with high-voltage lines or power lines. Doing so may result in damage or malfunction due to induction interference.

#### Connection

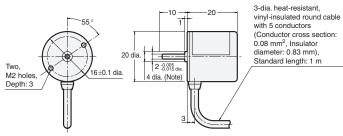
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

## **Dimensions**

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### Encoder E6J-CWZ1□



Note: The protrusion is a part of the shaft.

# E6J-CWZ1EA2 3-dia. heat-resistant, vinyl-insulated round cable with 5 conductors (Conductor cross section: 0.08 mm², Insulator diameter: 0.83 mm), Standard length: 1 m

#### **Accessories (Order Separately)**

Coupling E69-C02B

Refer to Accessories for details.

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